## **Sponsored Project**

**<u>Title:</u>** Automation Technologies

<u>Funded by</u>: Government of India, Ministry of Science and

Technology

Scheme: DST - FIST (Level I) for Post Graduate Teaching Research

Facility

Order No: SR/FST/ETI-399 dated 7th June 2016

Grant(Rs): 259.00 Lakhs

#### **Facility**

Factory Automation (Drives and controls) - PLC and Servo set up with pulse / network output, Micro PLC and HMI set up, Integrated FA set up, Motion controller set up, Modular PLC set up

<u>Gantry based FMS</u> - 2 axes high speed CNC gantry (15 kg payload), Gripper Index Unit, input and output conveyor, Pre and post gauge mounting

AGV based FMS - CNC Turn and Mill Centres, 2 /3 Axes loading and unloading Arm, ASRS, Vision station

Industrial Robotics - Industrial Robot -16Kg pay load in working cell with controller and teach pendant, PLC with device net communication, Gripper and Magazines, path programming software

<u>Sensorics</u> - Integrated Sensor board with interface

ASI System, RFID System, Ultrasonic System, Photoelectric System, Encoders, Vision Systems

<u>Hydraulic and Pneumatic Control Systems</u> - Industrial Mobile Hydraulics / Pneumatics

Double sided Work Stations with all accessories for Basic HP and Electric HP system

#### **Coordinators:**

Prof. Vijay Desai and Dr. Navin Karanth

#### **Utilization**

- To augment Theory and practical courses of Mechatronics and Manufacturing PG programs
- To carry out project works of Mechatronics and Manufacturing PG programs
- To support Automation related experimental work of PhD program
- To provide training to UG students

# **Industry Institute Interaction**

Title: Hexagon Next Gen 3D Lab

Funded by : Hexagon Capability Center India Private Limited,

Hyderabad & NITK, Surathkal

**Scheme:** Industry Institute Interaction Initiative

**Grant(Rs):** 7.17 Cr.

| <ul> <li>Plant models for</li> </ul>   |
|--|
| various industry segments  • Equipment and Piping  • Structural models for various industry segments |
| Dr. Mrityunjay   |
| •  |

## **Sponsored Project**

<u>Title:</u> Centre for system Design (CSD)

<u>Funded by:</u> Ministry of Human Resource and Development (MHRD),

GOI

<u>Scheme:</u> NITK and National Instruments Ltd. Industry Collaboration

Grant(Rs): 500.00 Lakhs

Title: SOLVE Lab [Phase - 1 and Phase -- 2]

<u>Funded by:</u>Ministry of Human Resource and Development (MHRD),

GOI

Scheme: NMEICT (National Mission on Education through ICT) -

Virtual Labs

<u>Grant(Rs):</u> 900.00 Lakhs

Title: Remote Triggered Lab

Funded by: Ministry of Human Resource and Development (MHRD),

GOI

Scheme: NMEICT (National Mission on Education through ICT) -

Virtual Labs

Grant(Rs): 150.00 Lakhs

### **Facility**

 $\frac{Accelerometers}{Accelerometers} - YMC \ (10mV/g \ , \ 100 \ mV/g), Kistler 50g, \ 500 \ g \ PCB$  Shear Accelerometer 10 mV/g, 100 mV/g

<u>Force Sensors</u> - Kistler (5, 50, 250 & 500 lbf);HBM S2 and S9; HBM Strain gauge based Force sensor (±10kN and ±1kN )

<u>Pressure sensor</u> - (SENSYM19C200PG4K , 19C100PA4K and 19C005G5)

National Instruments Data Acquisition systems and Lab VIEW (V2016)

<u>Coordinators:</u> Prof. K V Gangadharan, Dr. Pruthviraj U, Prof. Vijay Desai, Dr. Navin Karanth, Dr. Mohit T, Prof. Panduranga Vittal, Dr. Vidya Shetty, Prof. Ravikiran Kadoli







<u>Project Title:</u>- Development of Cost Effective Magneto-Rheological (MR) Fluid Damper in Two wheelers and Four Wheelers Automobile to Improve Ride Comfort and Stability

Budget:- Rs. 3.55 Crores Time Period: 2017-2020

<u>Principal Investigator</u>: **Dr. Hemantha Kumar**, Dept. of Mechanical Engineering, NITK

Co -Investigators

Prof. C.Sujatha

Dept. of Mechanical Engineering, IIT Madras

Prof. K.V.Gangadharan

Dept. of Mechanical Engineering, NITK

Dr. Sharnappa J.

Dept. of Mechanical Engineering, NITK

Dr. Mohd.Rizwan Rahman

Dept. of Material and Metallurgy Engg. NITK

Dr. Sheron F

Dept. of Electrical and Electronics Engg. NITK.

Dr. Sandesh S

Senior Manager, Ashok Leyland Ltd. Chennai

Mr. Rajasekharan Scientific Advisor, Rambal Ltd. Chennai

**Academic Collaborators** 





**Industrial Collaborators** 



